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## • Conjugate Vectors

Give three vectors a, b and c so that the three vectors form a conjugate system of vectors w.r.t. the matrix

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 3 & 1 \\ 1 & 1 & 9 \end{pmatrix}$$

We can fix the first vector. Let  $a = (1,0,0)^T$ , then  $a^T A = (1,1,1)$ . By inspecting  $a^T A$  we can set the second vector to  $b = (1,1,-2)^T$ , since  $a^T A b = 0$  iff a and b are conjugate to symmetric matrix A. Then we can set  $c = (x, y, z)^T$  and find a solution for it.

$$\left\{ \begin{array}{l} a^T A c = 0 \\ b^T A c = 0 \end{array} \right. \Leftrightarrow \left\{ \begin{array}{l} x + y + z = 0 \\ 2y - 16z = 0 \end{array} \right. \Leftrightarrow \left\{ \begin{array}{l} x + y + z = 0 \\ y = 8z \end{array} \right. \Leftrightarrow \left\{ \begin{array}{l} x = -9z \\ y = 8z \end{array} \right. \Rightarrow \left\{ \begin{array}{l} x = -9z \\ y = 8z \end{array} \right.$$

We can assign any value to z. Let'ss say that we pick z = 1, then the three conjugate vectors we find are  $a = (1, 0, 0)^T$ ,  $b = (1, 1, -2)^T$  and  $c = (-9, 8, 1)^T$ .

## • Example to apply the Conjugate Gradient Method

Minimize  $q(\mathbf{x}) = \frac{1}{2}\mathbf{x}^T \mathbf{A}\mathbf{x} - \mathbf{b}^T \mathbf{x}$ , where

$$\mathbf{A} = \begin{pmatrix} 1 & 1 \\ 1 & 4 \end{pmatrix}, \mathbf{b} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

starting from  $\mathbf{x}_1 = (0, 0)^T$ .

## Solution:

Initial search direction:

$$\mathbf{s}_1 = -\mathbf{g}_1 = -\nabla q(\mathbf{x}_1) = \mathbf{b} - \mathbf{A}\mathbf{x}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 1 & 1 \\ 1 & 4 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Step size:

$$\lambda_1 = \frac{-\mathbf{g}_1^T \mathbf{s}_1}{\mathbf{s}_1^T \mathbf{A} \mathbf{s}_1} = \frac{2}{7}$$

Next point:

$$\mathbf{x}_2 = \mathbf{x}_1 + \lambda_1 \mathbf{s}_1 = \begin{pmatrix} 2/7\\2/7 \end{pmatrix}$$

Next search direction:

$$\mathbf{s}_2 = -\mathbf{g}_2 + \beta_2 \mathbf{s}_1$$

where

$$\mathbf{g}_2 = 
abla q(\mathbf{x}_2) = \mathbf{A}\mathbf{x}_2 - \mathbf{b} = \left( egin{array}{c} -3/7 \\ 3/7 \end{array} 
ight)$$

and

$$\beta_2 = \frac{\mathbf{g}_2^T \mathbf{g}_2}{\mathbf{g}_1^T \mathbf{g}_1} = \frac{9}{49}$$

 $\operatorname{So},$ 

$$\mathbf{s}_2 = \left(\begin{array}{c} 30/49\\ -12/49 \end{array}\right)$$

Step size:

$$\lambda_2 = \frac{-\mathbf{g}_2^T \mathbf{s}_2}{\mathbf{s}_2^T \mathbf{A} \mathbf{s}_2} = \frac{7}{6}$$

Next point:

$$\mathbf{x}_3 = \mathbf{x}_2 + \lambda_2 \mathbf{s}_2 = \left(\begin{array}{c} 1\\ 0 \end{array}\right)$$

 $\mathbf{s}_1$  and  $\mathbf{s}_2$  are conjugate, *i.e.*,  $\mathbf{s}_1^T \mathbf{A} \mathbf{s}_2 = 0$ , and  $\mathbf{x}_3$  is the optimal solution since  $\nabla q(\mathbf{x}_3) = \mathbf{A} \mathbf{x}_3 - \mathbf{b} = \mathbf{0}$ .

In theory, the method has the property that, if exact arithmetic is used, convergence will occur in at most n iterations.